Data-Driven Conditional Robust Optimization

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Canada

Motivating example

- Returns of different assets are unknown but may depend on historical returns, economic factors, investor sentiments via social media.
- Portfolio manager can formulate an allocation problem to minimize the value-at-risk (VaR) of the portfolio while preserving an expected return above a given target.

What is contextual stochastic optimization?

- Optimization problems arising in practice almost always involve **unknown parameters** $\xi \in \mathbb{R}^{m_\xi}$
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- **Contextual Optimization**:
  - Optimizes a policy, $\boldsymbol{x} : \mathbb{R}^{m_\psi} \to \mathcal{X}$
    - I.e., action $x \in \mathcal{X}$ is adapted to the observed context ψ
  - **Contextual Stochastic Optimization** problem minimizes the expected cost of running the policy over the joint distribution of (ψ, ξ):

$$\min_{\boldsymbol{x}(\cdot)} \mathbb{E}[c(\boldsymbol{x}(\psi), \xi)] \Leftrightarrow \quad \boldsymbol{x}^*(\psi) \in \arg\min_{x \in \mathcal{X}} \mathbb{E}[c(x, \xi)|\psi] \text{ a.s.}$$

What is conditional robust optimization?

- We introduce a novel **Contextual Robust Optimization** paradigm for solving contextual optimization problems in a risk-averse setting:

$$\text{(Robust-CO)} \qquad \min_{\boldsymbol{x}(\cdot)} \max_{\psi\in\mathcal{V},\xi\in\mathcal{U}(\psi)} c(\boldsymbol{x}(\psi),\xi)$$

  where $\mathcal{U}(\psi)$ is a **conditional uncertainty set** designed to contain with high probability the realization of ξ conditionally on observing ψ.

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- A weak interchangeability property states:

$$\boldsymbol{x}^*(\cdot) \in \arg\min_{\boldsymbol{x}(\cdot)} \max_{\psi \in \mathcal{V}, \xi \in \mathcal{U}(\psi)} c(\boldsymbol{x}(\psi), \xi)$$

$$\Leftarrow \quad \boldsymbol{x}^*(\psi) \in \underbrace{\arg\min_{x \in \mathcal{X}} \max_{\xi \in \mathcal{U}(\psi)} c(x, \xi)}_{\textbf{Conditional Robust Optimization (CRO)}} \quad , \forall \psi \in \mathcal{V}$$

Desirable coverage properties for $\mathcal{U}(\psi)$

The field of conformal prediction identifies two important properties for conditional uncertainty sets

- Marginal coverage property: $\mathbb{P}(\xi \in \mathcal{U}(\psi)) \geq 1 - \epsilon$
- Conditional coverage property: $\mathbb{P}(\xi \in \mathcal{U}(\psi) | \psi) \geq 1 - \epsilon$ a.s.
- Conditional coverage $\Rightarrow$ Marginal coverage

E.g., target coverage $1 - \epsilon = 90\%$:

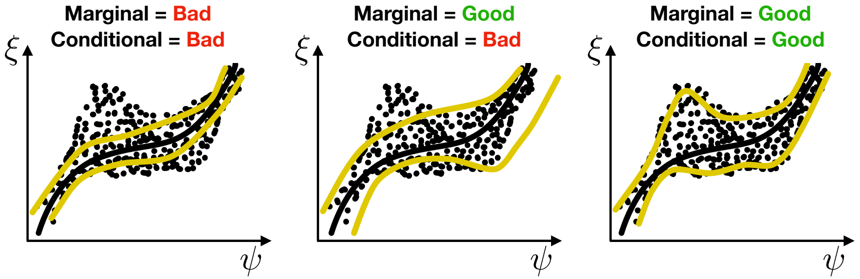

Image from Angelopoulos and Bates, A Gentle Introduction to Conformal Prediction and Distribution-Free Uncertainty Quantification, CoRR, 2021.

Related work in operations research literature

- Contextual Stochastic Optimization:
  - Hannah et al. [2010], Bertsimas and Kallus [2020], ...: Conditional distribution estimation used to formulate and solve the CSO problem.
  - Donti et al. [2017], Elmachtoub and Grigas [2022], ...: End-to-end paradigm applied to solve the data driven CSO problem.
- Distributionally Robust CSO:
  - Bertsimas et al. [2022], McCord [2019], Wang and Jacquillat [2020], Kannan et al. [2020]: DRO approaches with ambiguity sets centered at the estimated conditional distribution
- Data-driven Robust Optimization:
  - Goerigk and Kurtz [2023], Johnstone and Cox [2021]: learns a traditional "non-contextual" uncertainty set using deep learning, and conformal prediction.
  - Ohmori [2021], Sun et al. [2023]: calibrates a box or ellipsoidal set to cover the realizations of a kNN-based or residual-based conditional distribution.
  - Chenreddy et al. [2022] learns a contextual uncertainty set using an integrated clustering then classification approach

Presentation overview

Outline

Deep Data-Driven Robust Optimization (DDDRO)

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$$\min_{x \in \mathcal{X}} \max_{\xi \in \mathcal{U}} c(x, \xi),$$

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$$\mathcal{U}(W, R) = \left\{ \xi \in \mathbb{R}^{m_\xi} : \|f_W(\xi) - \bar{f}_0\| \leq R \right\},$$

where $f_W : \mathbb{R}^{m_\xi} \to \mathbb{R}^d$ is a deep neural network (DNN).

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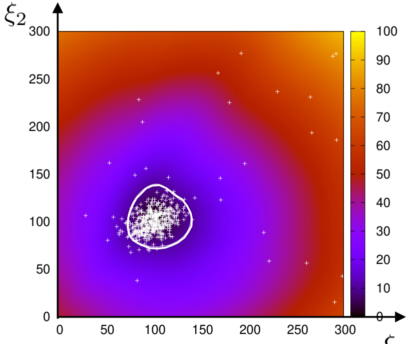
where $f_W : \mathbb{R}^{m_\xi} \to \mathbb{R}^d$ is a deep neural network (DNN).

- Given a dataset $\mathcal{D}_\xi = \{\xi_1, \xi_2 \ldots \xi_N\}$, $\mathcal{U}$ is designed by training a NN to minimize the one-class classification loss

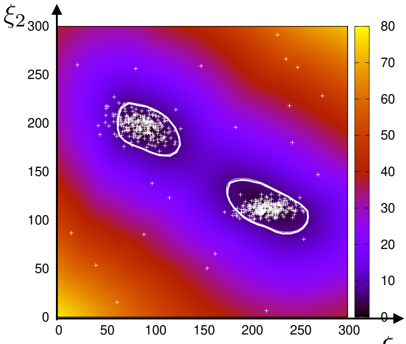
$$\min_W \frac{1}{N} \sum_{i=1}^{N} \|f_W(\xi_i) - \bar{f}_0\|^2,$$

where $\bar{f}_0 := (1/N) \sum_{i \in [N]} f_{W_0}(\xi_i)$ and the radius R is calibrated for $1 - \epsilon$ coverage on the data set.

Illustrative examples



(a) Gaussian data, NN set.



(c) Mixed Gaussian data, NN set.

Images from Goerigk and Kurtz. Data-driven robust optimization using deep neural networks. Computers and Operational Research, 151(C), 2023

Solving robust optimization with deep uncertainty sets

- When using piecewise affine activation functions, $\mathcal{U}(W, R)$ can be represented as:

$$\mathcal{U}(W,R) := \left\{ \xi \;\middle|\; \begin{array}{c} \exists u \in \{0,\,1\}^{d\times K\times L},\ \zeta \in \mathbb{R}^{d\times L},\ \phi \in \mathbb{R}^{d\times L} \\ \sum_{k=1}^{K} u_j^{k,\ell} = 1,\ \forall j,\ell \\ \phi^1 = W^1\xi \\ \zeta_j^\ell = \sum_{k=1}^{K} u_j^{k,\ell} a_k^\ell \phi_j^\ell + \sum_{k=1}^{K} u_j^{k,\ell} b_k^\ell,\ \forall j,\ell \\ \phi^\ell = W^\ell \zeta^{\ell-1},\ \forall \ell \geq 2 \\ \sum_{k=1}^{K} u_j^{k,\ell} \underline{\alpha}_k^\ell \leq \phi_j^\ell \leq \sum_{k=1}^{K} u_j^{k,\ell} \overline{\alpha}_k^\ell,\ \forall j,\ell \\ \|\zeta^L - \bar{f}_0\| \leq R \end{array} \right\}$$

- The problem $\max_{\xi\in\mathcal{U}(W,R)} c(x,\xi)$ can therefore be formulated as a mixed-integer second order cone program when $c(x,\xi)$ is linear.

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- The problem $\max_{\xi\in\mathcal{U}(W,R)} c(x,\xi)$ can therefore be formulated as a mixed-integer second order cone program when $c(x,\xi)$ is linear.
- This can be integrated in a cutting plane method for solving the RO:

$$\begin{aligned} \min_{x\in\mathcal{X},t} \quad & t \\ \text{subject to} \quad & c(x,\xi) \leq t,\ \forall \xi \in \mathcal{U}' \subset \mathcal{U}(W,R) \end{aligned}$$

Outline

Deep Cluster then Classify (DCC)

- We use $\mathcal{D} := \{(\psi_1, \xi_1), \ldots, (\psi_N, \xi_N)\}$ to design data-driven conditional uncertainty sets $\mathcal{U}(\psi)$.

- This approach reduces the side-information ψ to a set of K different clusters and designs customized sets, i.e., $\mathcal{U}(\psi) := \mathcal{U}_{a(\psi)}$
  - $a : \mathbb{R}^{m_\psi} \to [K]$ is a trained K-class cluster assignment function
  - Each $\mathcal{U}_k$, for $k = 1, \ldots, K$, is an uncertainty sets for ξ calibrated on the dataset $\mathcal{D}_\xi^k := \cup_{(\psi,\xi)\in\mathcal{D}:a(\psi)=k}\{\xi\}$ as in Goerigk and Kurtz [2023].

Deep clustering using auto-encoder/decoder networks

We use an auto-encoder and decoder network to identify $a(\cdot)$,

$$\mathcal{L}^1(V,\theta) := \frac{1-\alpha_K}{N}\sum_{i=1}^{N}\|g_{V_D}(g_{V_E}(\psi_i)) - \psi_i\|^2 + \frac{\alpha_K}{N}\sum_{i=1}^{N}\|g_{V_E}(\psi_i) - \theta^{a(\psi_i)}\|^2 ,$$

where

$$a(\psi) := \operatorname*{argmin}_{k\in[K]} \|g_{V_E}(\psi) - \theta^k\|$$

and V_E and V_D are the network parameters.

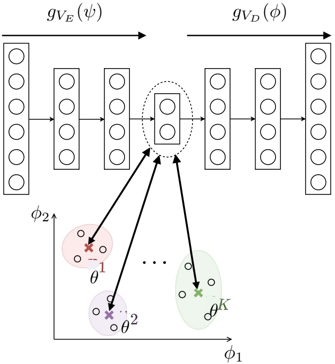

Image adapted from Fard et al. Deep k-means: Jointly clustering with k-means and learning representations. Pattern Recognition Letters, 138:185–192, 2020

Integrated DCC addresses shortcoming of DCC

1. DCC fails to tackle the conditional uncertainty set learning problem as a whole
   - Solution: IDCC optimizes V_E, V_D, θ, and $\{W^k\}_{k=1}^K$ jointly using a loss function that trades-off between the objectives used for clustering and each of the K versions of one-class classifiers

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2. DCC struggles for cases where clear separation of clusters isn't possible.
   - Solution: IDCC trains a parameterized random assignment policy $\tilde{a}(\psi) \sim \pi(\psi)$:

$$\mathbb{P}(\tilde{a}(\psi) = k) = \pi_k(\psi) := \frac{\exp\{-\beta\|g_V(\psi) - \theta^k\|^2\}}{\sum_{k'=1}^K \exp\{-\beta\|g_V(\psi) - \theta^{k'}\|^2\}}$$

The **random** uncertainty set is $\tilde{\mathcal{U}}(\psi) := \mathcal{U}(W^{\tilde{a}(\psi)}, R^{\tilde{a}(\psi)})$

Experiments

Robust portfolio optimization with market data

- Decision model:

$$x^*(\psi) := \arg \min_{x:\sum_{i=1}^n x_i=1,\ x\geq 0} \max_{\xi\in\mathcal{U}(\psi)} \xi^\intercal x$$

  which captures the need to invest one unit of wealth among the available assets while minimizing risk exposure.

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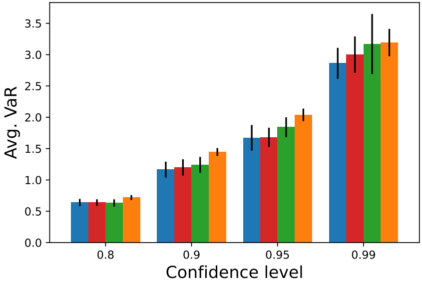
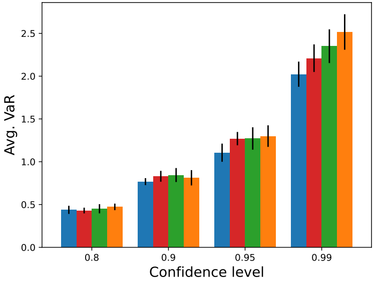
- Performance metric: out-of-sample VaR of $\xi^T x(\psi)$

Portfolio optimization: Comparison of avg. VaR across portfolio simulations



(a) 2018



(b) 2019

Ellipsoid DDDRO DCC IDCC

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Task-based CRO

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- In this next part, we propose **Task-based Conditional Robust Optimization** that promotes **performance** and **conditional coverage**.

Estimate-then-Optimize with continuous adaptation

- We consider a continuously adapted conditional ellipsoidal set:

$$\mathcal{U}_\theta(\psi) := \{\ \xi \in \mathbb{R}^{m_\xi} : (\xi - \mu_\theta(\psi))^T \Sigma_\theta^{-1}(\psi)(\xi - \mu_\theta(\psi)) \leq R_\theta \},$$

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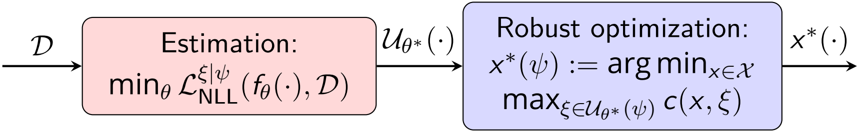
- Given a data set $\mathcal{D} = \{(\psi_1, \xi_1), (\psi_2, \xi_2) \ldots (\psi_N, \xi_N)\}$, an estimate-then-optimize (ETO) approach takes the form:



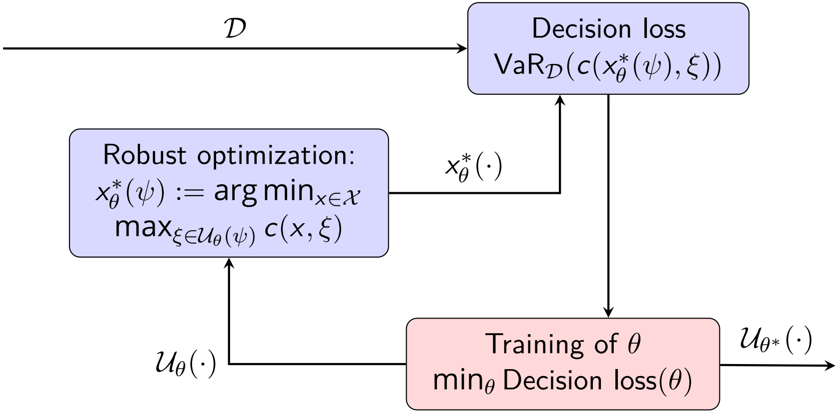
where $\mathcal{L}_{\text{NLL}}^{\xi|\psi}$ is the negative log likelihood for a conditional Gaussian density estimator (see Barratt and Boyd [2021]):

$$\xi \sim f_\theta(\psi) := \mathcal{N}(\mu_\theta(\psi), \Sigma_\theta(\psi))$$

and R_θ s.t. $\mathbb{P}_\mathcal{D}(\xi \in \mathcal{U}_\theta(\psi)) = 1 - \epsilon$

(Single) Task-based Set (TbS) training

A task-based approach learns the estimator by trying to minimize the decision loss, e.g. the portfolio risk based on VaR



Decision loss relaxation and derivatives

- Decision loss $\text{VaR}_{\mathcal{D}}(c(x^*_\theta(\psi), \xi))$ suffers from multiple local optima.

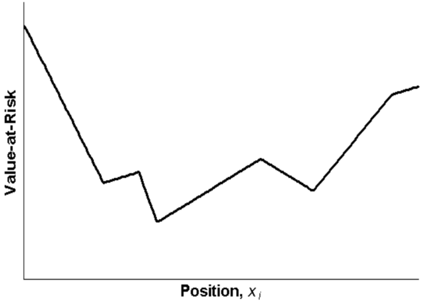


Figure 3: Simulation-based trade risk profile

Image from Mausser and Rosen, Beyond VaR: from measuring risk to managing risk, CIFEr, 1999.

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Figure 3: Simulation-based trade risk profile

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- We therefore replace it with upper bound $\text{CVaR}_{\mathcal{D}}(c(x_\theta^*(\psi), \xi))$.

$$\frac{\partial \text{CVaR}_{i\sim N}(y_{\tilde{i}})}{\partial y_i} = v_i(y) \text{ with } \boldsymbol{v}(\boldsymbol{y}) \in \underset{\boldsymbol{v}\in\mathbb{R}_+^M : \mathbb{1}^T\boldsymbol{v}=1, \boldsymbol{v}\leq((1-\alpha)N)^{-1}}{\text{argmax}} \boldsymbol{v}^T\boldsymbol{y}$$

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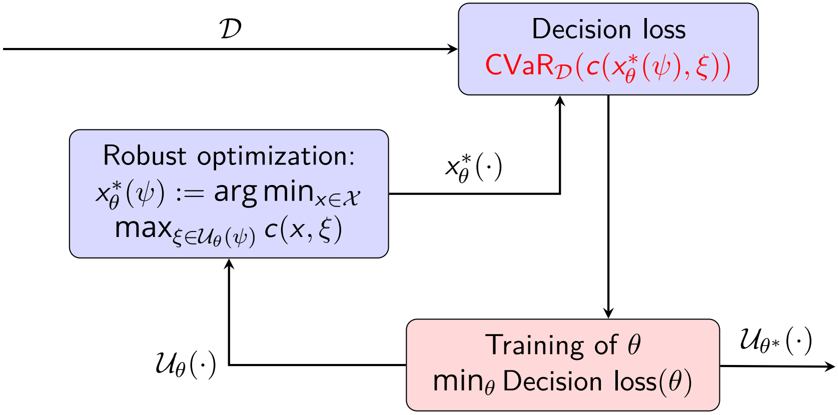

Robust optimization reformulation and derivatives

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- Using Fenchel duality, one can follow Ben-Tal et al. [2015] to reformulate the robust optimization problem as:

$$x^*_\theta(\psi) := \arg\min_{x\in\mathcal{X}} \max_{\xi\in\mathcal{U}_\theta(\psi)} c(x,\xi) = \arg\min_{v,x\in\mathcal{X}} \underbrace{\delta^*(v|\mathcal{U}_\theta(\psi)) - c_*(x,v)}_{f(x,v,\mathcal{U}_\theta(\psi))}$$

where the support function

$$\delta^*(v|\mathcal{U}_\theta(\psi)) := \sup_{\xi\in\mathcal{U}_\theta(\psi)} \xi^T v = \mu^T v + \sqrt{v^T\Sigma^{-1}v}$$

while the partial concave conjugate function is defined as

$$c_*(x,v) := \inf_{\xi} v^T\xi - c(x,\xi)$$

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- The derivatives of $x^*_\theta(\psi) := \arg\min_{v,x\in\mathcal{X}} f(x,v,\mathcal{U}_\theta(\psi))$ w.r.t. θ can be obtained using implicit differentiation (see Blondel et al. [2022])

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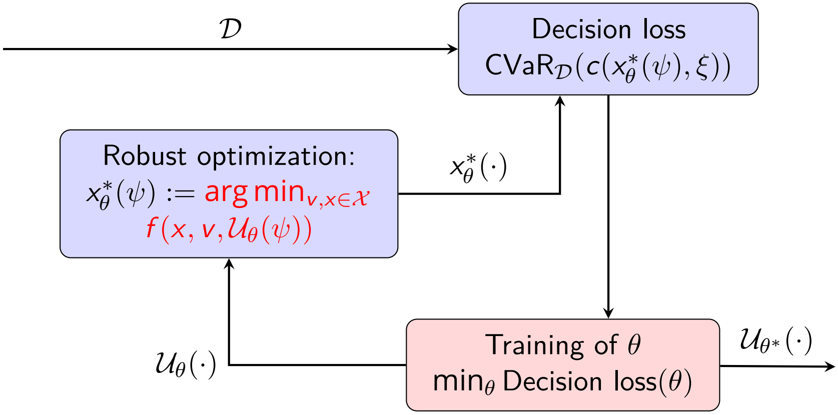

Second-task: Conditional coverage

Lemma

An uncertainty set $\mathcal{U}_\theta(\psi)$ *has an a.s. conditional coverage of* $1-\epsilon$ *if and only if*

$$\mathcal{L}_{CC}(\theta) := \mathbb{E}[\,(\mathbb{P}(\xi \in \mathcal{U}_\theta(\psi)|\psi) - (1-\epsilon))^2\,] = 0$$

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$$\widehat{\mathcal{L}}_{\mathsf{CC}}(\theta) := \mathbb{E}_{\mathcal{D}}[(g_{\phi^*(\theta)}(\psi) - (1-\epsilon))^2]$$

where $g_{\phi^*(\theta)}(\psi) \approx \mathbb{P}(\xi \in \mathcal{U}_\theta(\psi)|\psi)$ is obtained using logistic regression of membership variable $y(\psi, \xi; \theta) := \mathbb{1}\{\xi \in \mathcal{U}_\theta(\psi)\}$ on ψ.

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- I.e., letting the augmented data set

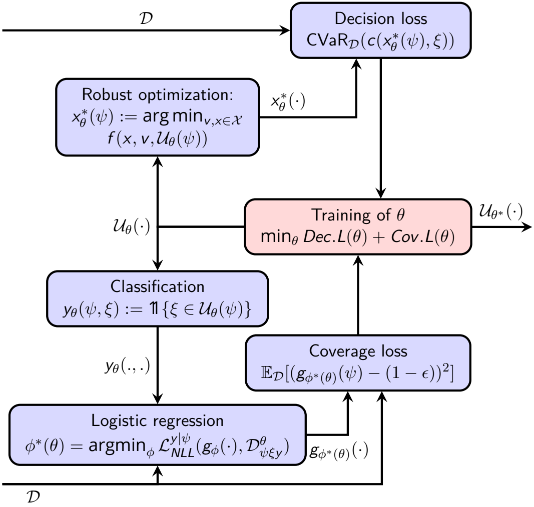
$$\mathcal{D}^\theta_{\psi\xi y} := \{(\psi_1, \xi_1, y(\psi_1, \xi_1; \theta)), \ldots, (\psi_N, \xi_N, y(\psi_N, \xi_N; \theta))\},$$

  one solves $\phi^*(\theta) \in \mathrm{argmin}_\phi\, \mathcal{L}^{y|\psi}_{NLL}(g_\phi(\cdot), \mathcal{D}^\theta_{\psi\xi y})$ with

$$g_\phi(\psi) := \frac{1}{1 + \exp^{\phi^T\psi + \phi_0}}$$

Double Task-based Set (DTbS) training

We train $\mathcal{U}_\theta(\psi)$ using the two tasks: produce good decision + produce good conditional coverage:



Comparative study with GMM environment

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- Data: 600 points for training, 400 for validation, 1000 for test
- Targeted confidence level of 90%
- Average is calculated over 10 runs

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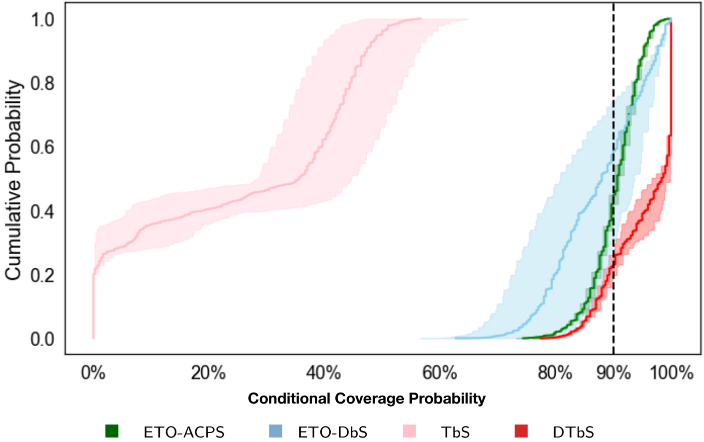
- Targeted confidence level of 90%
- Average is calculated over 10 runs

	ETO-ACPS	ETO-DbS	TbS	DTbS
Avg. CVaR	1.88 ± 0.09	1.66 ± 0.11	**1.38** ± 0.03	**1.32** $\pm$ 0.05
Avg. VaR	1.24 ± 0.06	1.01 ± 0.06	**0.89** ± 0.02	**0.85** $\pm$ 0.04
Avg. marginal cov.	**90%** $\pm 2\%$	$95\% \pm 4\%$	$52\% \pm 10\%$	$92\% \pm 1\%$

Comparative study with GMM environment



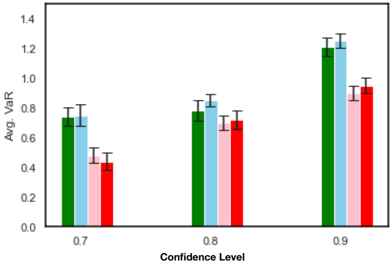
Portfolio optimization with market data

- Contextual info: Trading volume, volatility index (VIX), 10-year treasury yield index (TNX), oil index (CLF), S&P 500 (GSPC), gold price (GC=F), Dow Jones (DJI).
- Market data from Yahoo! Finance: 70 different stocks during period from 01/01/2012 to 31/12/2019 (2017-2019 reserved for test).
- Target confidence level of 70%, 80%, or 90%

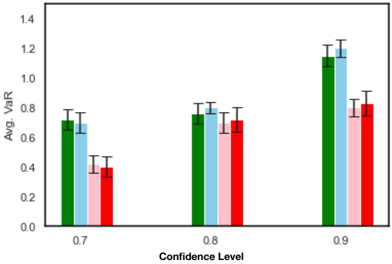
Model	Marginal coverage					
	2018			2019		
	70%	80%	90%	70%	80%	90%
ETO-ACPS	68%	78%	87%	71%	78%	89%
ETO-DbS	59%	75%	87%	61%	76%	86%
TbS	23%	24%	29%	26%	30%	32%
DTbS	71%	80%	93%	69%	78%	92%

Portfolio optimization with market data

- Contextual info: Trading volume, volatility index (VIX), 10-year treasury yield index (TNX), oil index (CLF), S&P 500 (GSPC), gold price (GC=F), Dow Jones (DJI).
- Market data from Yahoo! Finance: 70 different stocks during period from 01/01/2012 to 31/12/2019 (2017-2019 reserved for test).



(a) 2018



(b) 2019

ETO-ACPS ETO-DbS TbS DTbS

Outline

Concluding remarks

- We introduced a new contextual robust optimization approach for solving risk averse contextual optimization problems.
- In CRO, deep neural networks can be used to:
  - Represent richly structured uncertainty sets, e.g. DDDRO, IDCC
  - Adapt uncertainty set continuously to covariates, e.g. ETO-ACPS,..., DTbS.
- Two types of training procedures: “Estimate-then-optimize” vs. “Task-based”
- Two types of training objectives:
  - Decision performance: Producing decisions that achieve low VaR/CVaR
  - Statistical performance: achieving the right marginal/conditional coverage

Thank you

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